

FREE-BODY DIAGRAMS, EQUATIONS OF EQUILIBRIUM & CONSTRAINTS FOR A RIGID BODY

Today's Objective:

Students will be able to:

- a) Identify support reactions in 3-D and draw a free body diagram, and,
- b) apply the equations of equilibrium.



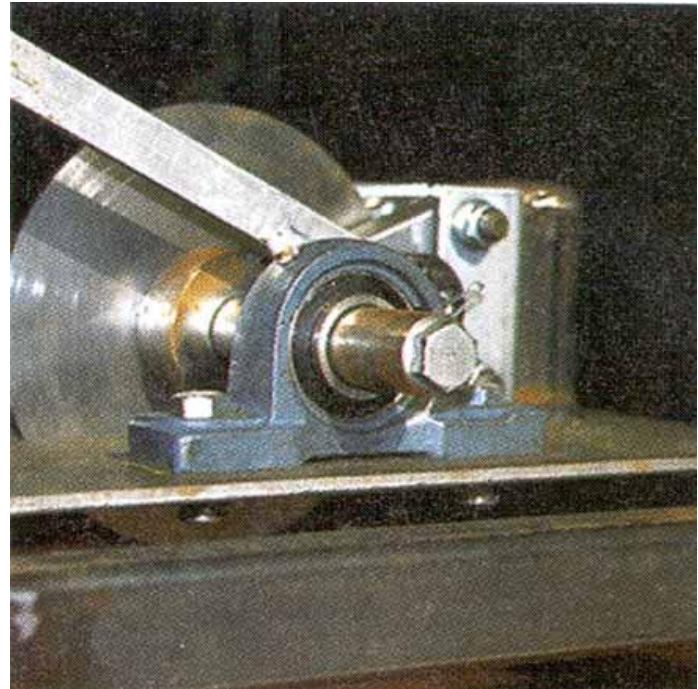
READING QUIZ

1. If a support prevents rotation of a body about an axis, then the support exerts a _____ on the body about that axis.
A) couple moment B) force
C) Both A and B. D) None of the above.
2. When doing a 3-D problem analysis, you have _____ scalar equations of equilibrium.

Enter a number corresponding to your answer.



APPLICATIONS

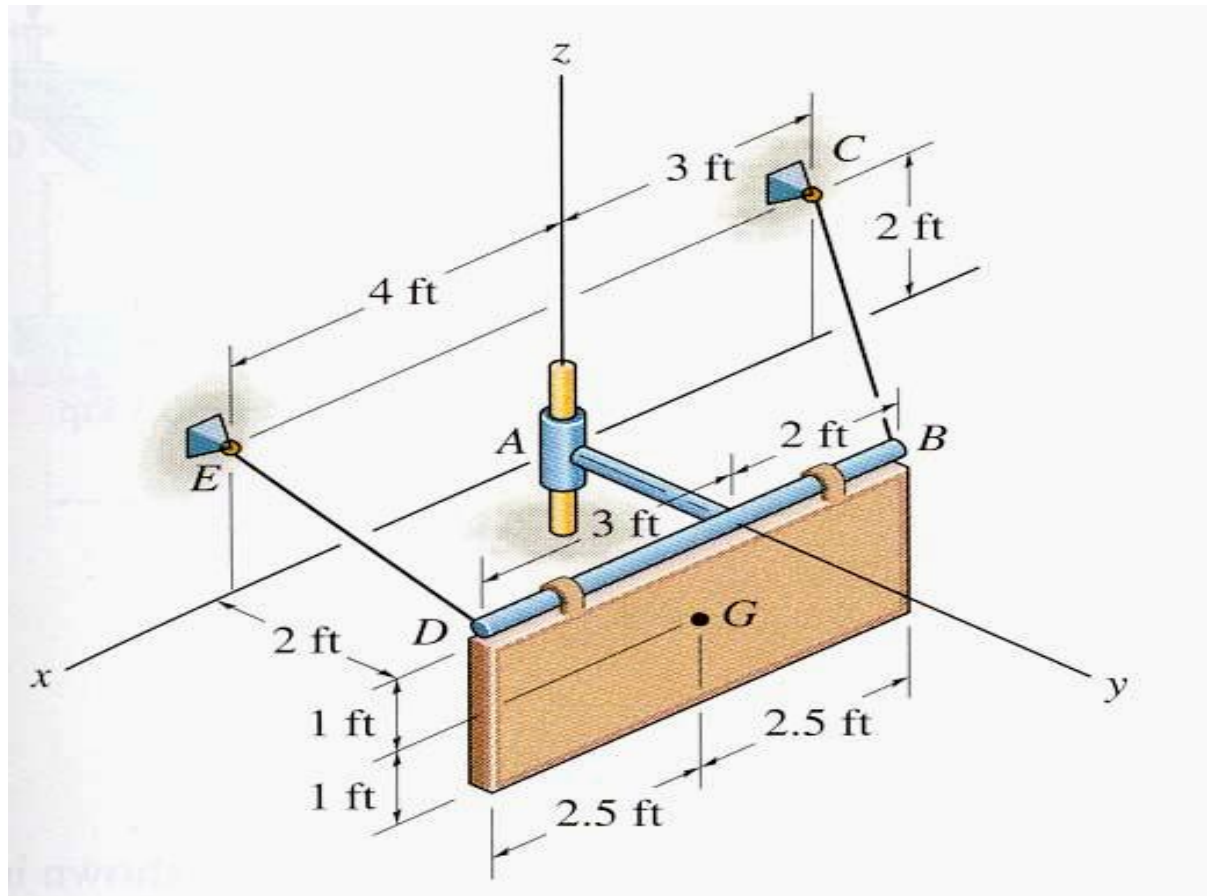


Ball-and-socket joints and journal bearings are often used in mechanical systems.

How can we determine the support reactions at these joints for a given loading?



APPLICATIONS (continued)



A 50 lb sign is kept in equilibrium using two cables and a smooth collar. How can we determine the reactions at these supports?



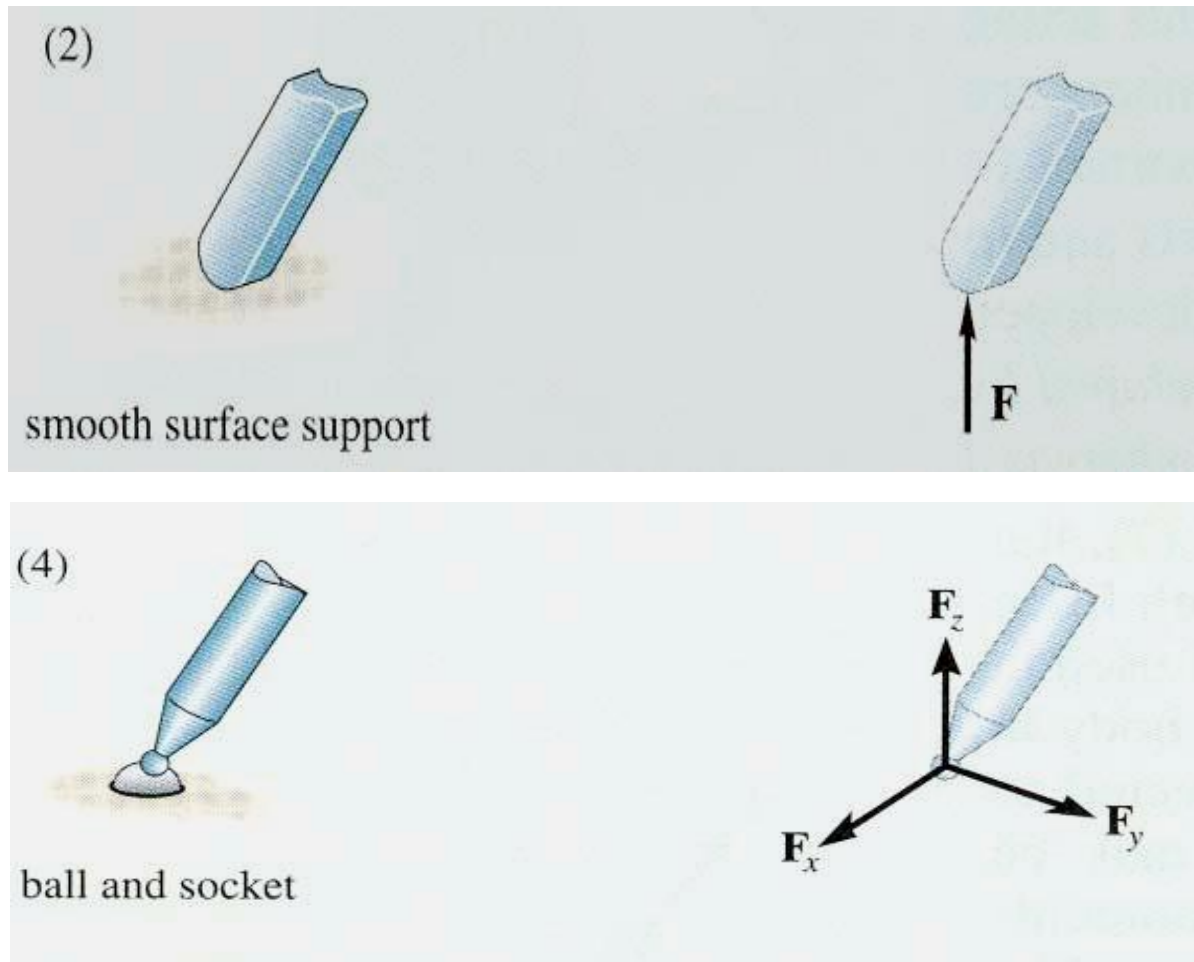
Equilibrium in Three Dimension

5.5 FREE-BODY DIAGRAMS

The first step in solving 3D equilibrium problems is to draw a free-body diagram of the body:

Support Reactions should be studied

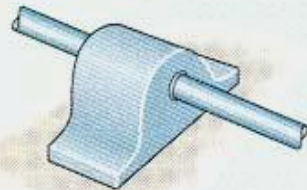
SUPPORT REACTIONS IN 3-D (Table 5-2)



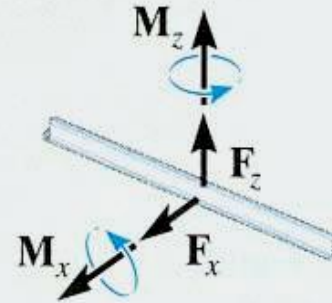
A few examples are shown above. Other support reactions are given in your text book (Table 5-2).

SUPPORT REACTIONS IN 3-D (Table 5-2)

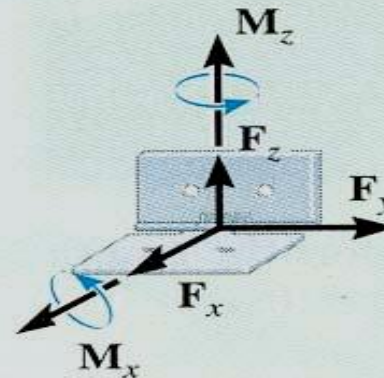
(5)



single journal bearing

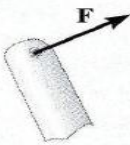
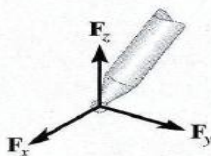
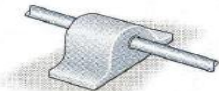
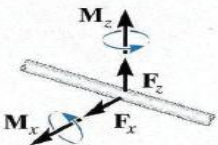


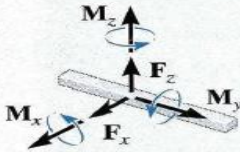
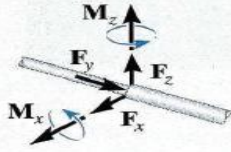
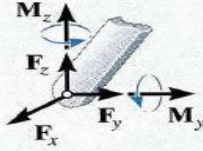
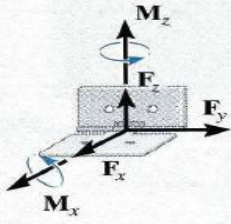
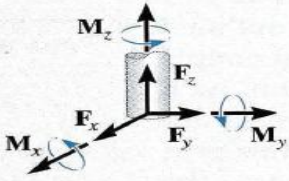
single hinge



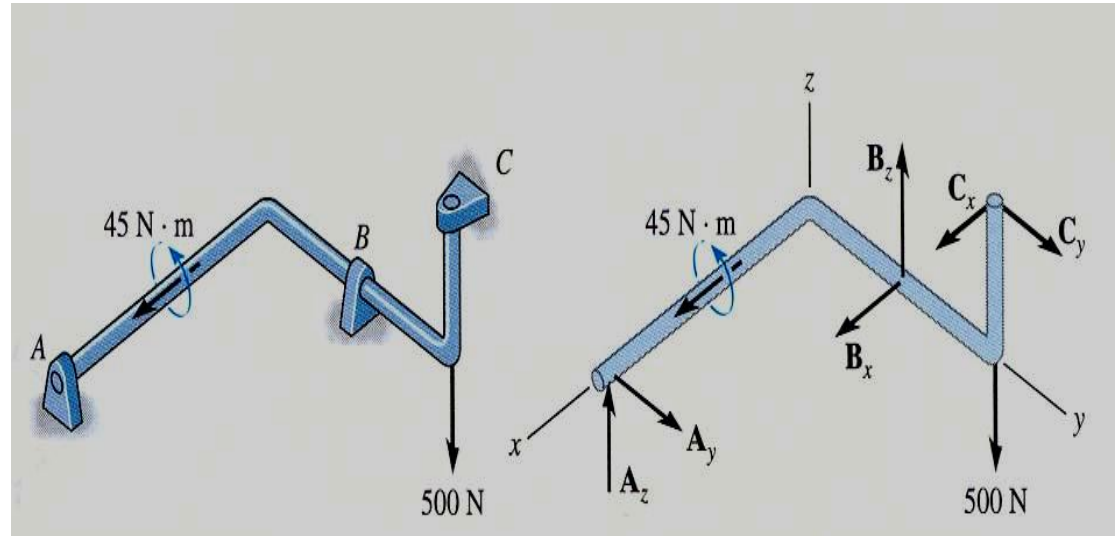
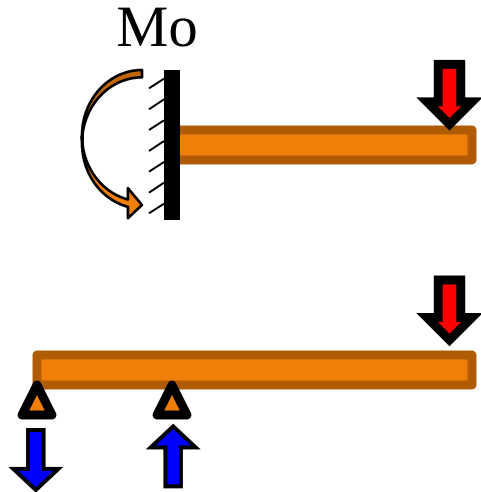
As a general rule, if a support prevents translation of a body in a given direction, then a reaction force acting in the opposite direction is developed on the body. Similarly, if rotation is prevented, a couple moment is exerted on the body by the support.

► **Table 5–2 Supports for Rigid Bodies Subjected to Three-Dimensional Force Systems**

Types of Connection	Reaction	Number of Unknowns
(1)  cable	 One unknown. The reaction is a force which acts away from the member in the known direction of the cable.	
(2)  smooth surface support	 One unknown. The reaction is a force which acts perpendicular to the surface at the point of contact.	
(3)  roller	 One unknown. The reaction is a force which acts perpendicular to the surface at the point of contact.	
(4)  ball and socket	 Three unknowns. The reactions are three rectangular force components.	
(5)  single journal bearing	 Four unknowns. The reactions are two force and two couple-moment components which act perpendicular to the shaft.	

Types of Connection	Reaction	Number of Unknown
(6)  single journal bearing with square shaft		Five unknowns. The reactions are two force and three couple-moment components.
(7)  single thrust bearing		Five unknowns. The reactions are three force and two couple-moment components.
(8)  single smooth pin		Five unknowns. The reactions are three force and two couple-moment components.
(9)  single hinge		Five unknowns. The reactions are three force and two couple-moment components.
(10)  fixed support		Six unknowns. The reactions are three force and three couple-moment components.

IMPORTANT NOTE



A single bearing or hinge can prevent rotation by providing a resistive couple moment. However, it is usually preferred to use two or more properly aligned bearings or hinges. Thus, in these cases, only force reactions are generated and there are no moment reactions created.



5.6 EQUATIONS OF EQUILIBRIUM

As stated earlier, when a body is in equilibrium, the net force and the net moment equal zero, i.e., $\sum \mathbf{F} = 0$ and $\sum \mathbf{M}_O = 0$.

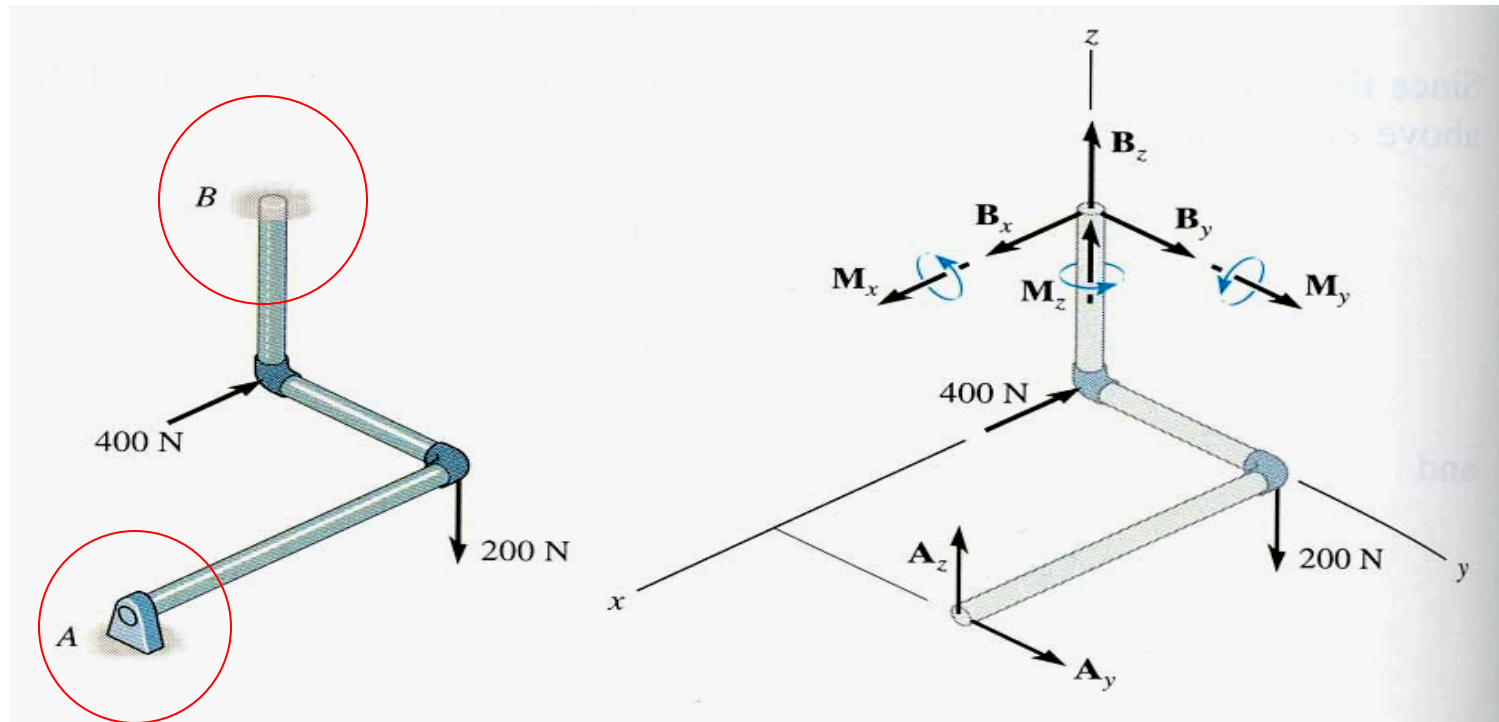
These two vector equations can be written as six scalar equations of equilibrium (EofE). These are

$$\sum F_X = \sum F_Y = \sum F_Z = 0$$

$$\sum M_X = \sum M_Y = \sum M_Z = 0$$

The moment equations can be determined about any point. Usually, choosing the point where the maximum number of unknown forces are present simplifies the solution. Those forces do not appear in the moment equation since they pass through the point. Thus, they do not appear in the equation.

5.7 CONSTRAINTS FOR A RIGID BODY

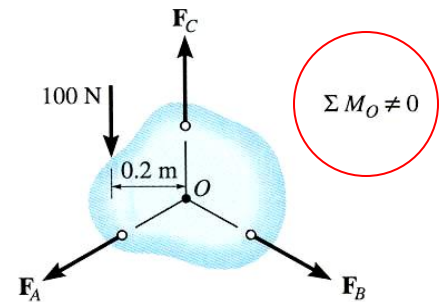
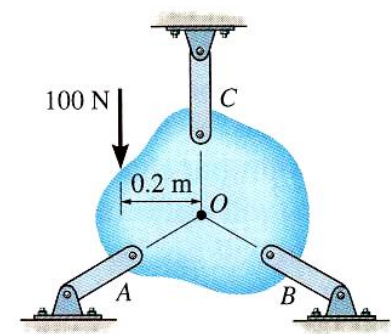
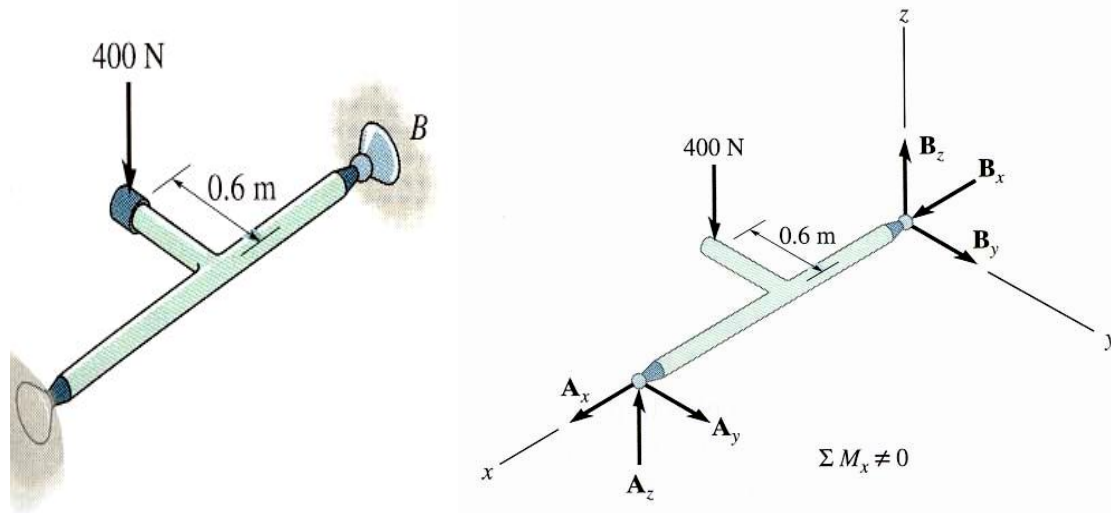


Redundant Constraints: When a body has more supports than necessary to hold it in equilibrium, it becomes statically indeterminate.

A problem that is statically indeterminate has more unknowns than equations of equilibrium.

Are statically indeterminate structures used in practice? Why or why not?

IMPROPER CONSTRAINTS



Here, we have 6 unknowns but there is nothing restricting rotation about the x axis.

In some cases, there may be as many unknown reactions as there are equations of equilibrium. However, if the supports are not properly constrained, the body may become unstable for some loading cases.

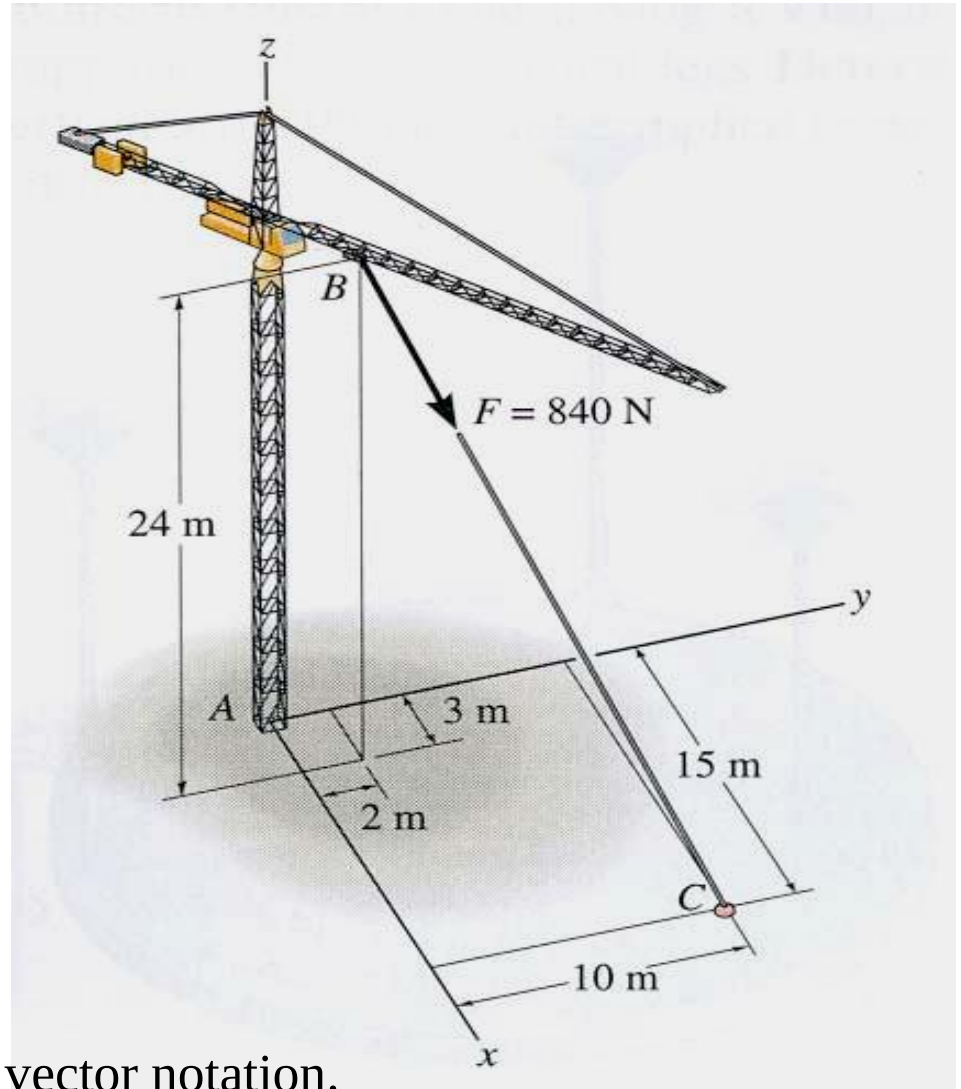
EXAMPLE

Given: The cable of the tower crane is subjected to 840 N force. A fixed base at A supports the crane.

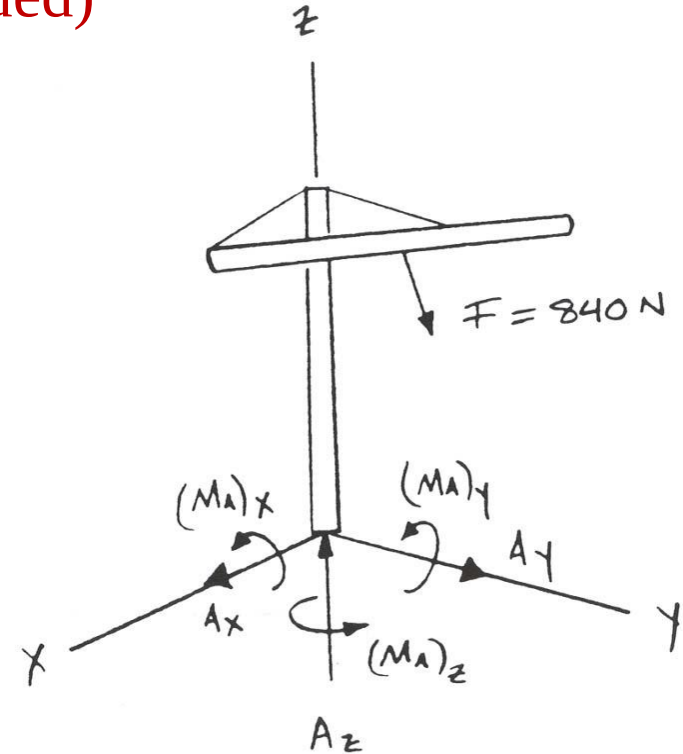
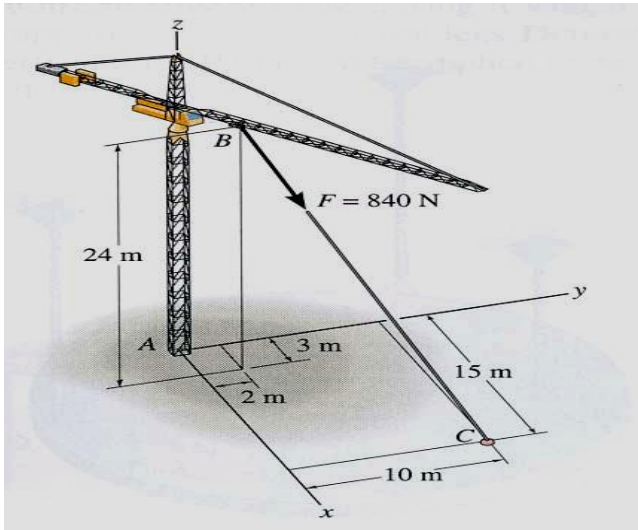
Find: Reactions at the fixed base A.

Plan:

- Establish the x, y and z axes.
- Draw a FBD of the crane.
- Write the forces using Cartesian vector notation.
- Apply the equations of equilibrium (vector version) to solve for the unknown forces.



EXAMPLE (continued)



$$\mathbf{r}_{BC} = \{12 \mathbf{i} + 8 \mathbf{j} - 24 \mathbf{k}\} \text{ m}$$

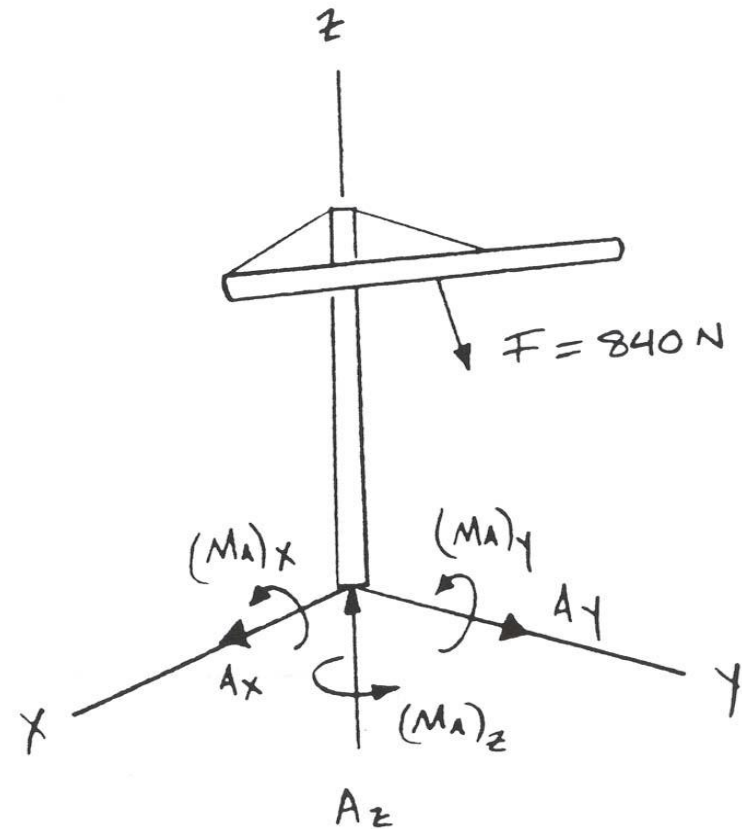
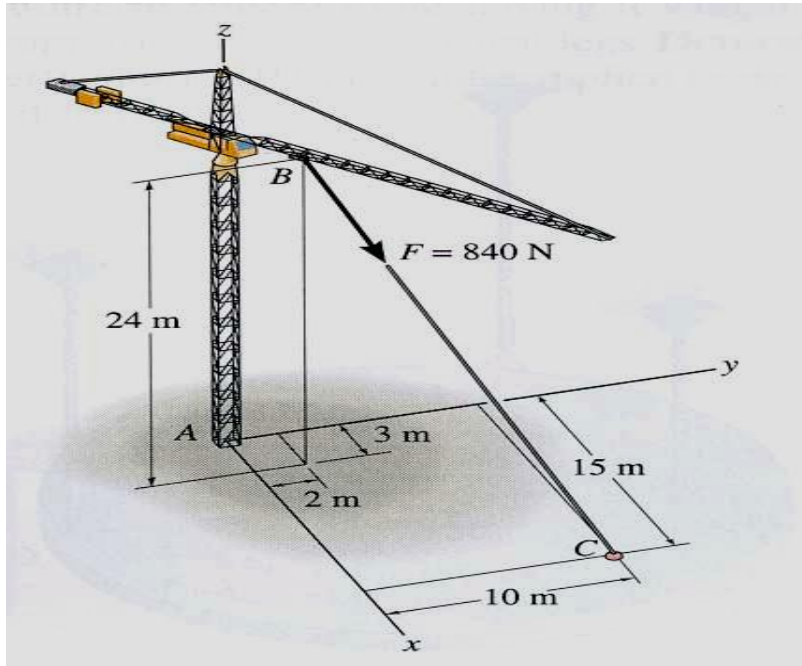
$$\mathbf{F} = F [\mathbf{u}_{BC}] \text{ N}$$

$$= 840 [12 \mathbf{i} + 8 \mathbf{j} - 24 \mathbf{k}] / (12^2 + 8^2 + (-24^2))^{1/2}$$

$$= \{360 \mathbf{i} + 240 \mathbf{j} - 720 \mathbf{k}\} \text{ N}$$

$$\mathbf{F}_A = \{A_X \mathbf{i} + A_Y \mathbf{j} + A_Z \mathbf{k}\} \text{ N}$$

EXAMPLE



From E-of-E we get, $\mathbf{F} + \mathbf{F}_A = \mathbf{0}$

$$\{(360 + A_x)\mathbf{i} + (240 + A_y)\mathbf{j} + (-720 + A_z)\mathbf{k}\} = \mathbf{0}$$

Solving each component equation yields

$$\underline{A_x = -360 \text{ N}}, \quad \underline{A_y = -240 \text{ N}}, \quad \text{and} \quad \underline{A_z = 720 \text{ N}}.$$

EXAMPLE

Sum the moments acting at point A.

$$\sum \mathbf{M} = \mathbf{M}_A + \mathbf{r}_{AC} \times \mathbf{F} = 0$$

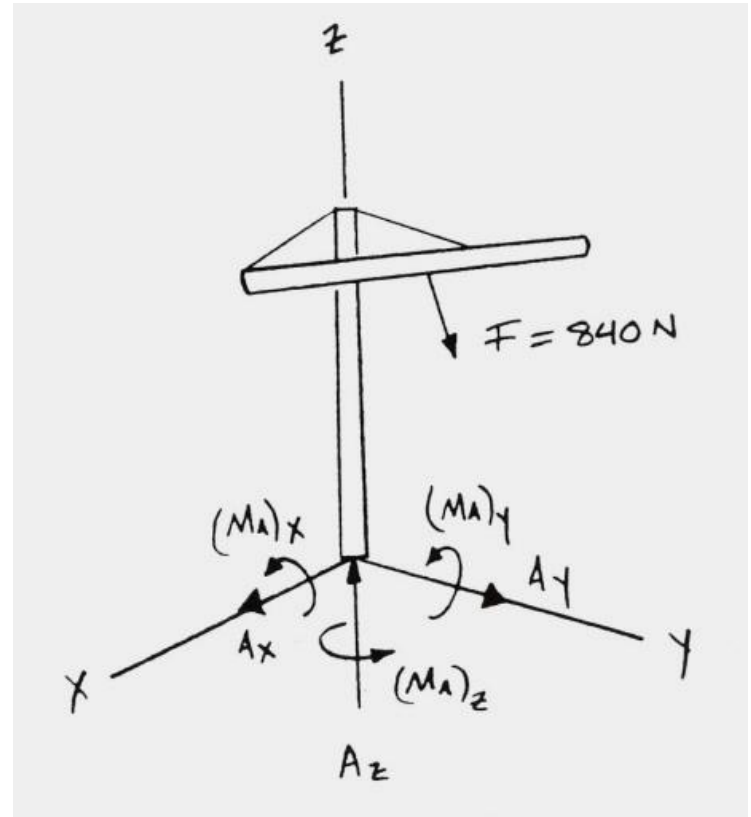
$$= M_{AX} \mathbf{i} + M_{AY} \mathbf{j} + M_{AZ} \mathbf{k} +$$

$$+ \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 15 & 10 & 0 \\ 360 & 240 & -720 \end{vmatrix} = 0$$

$$= M_{AX} \mathbf{i} + M_{AY} \mathbf{j} + M_{AZ} \mathbf{k} - 7200 \mathbf{i} + 10800 \mathbf{j} = 0$$

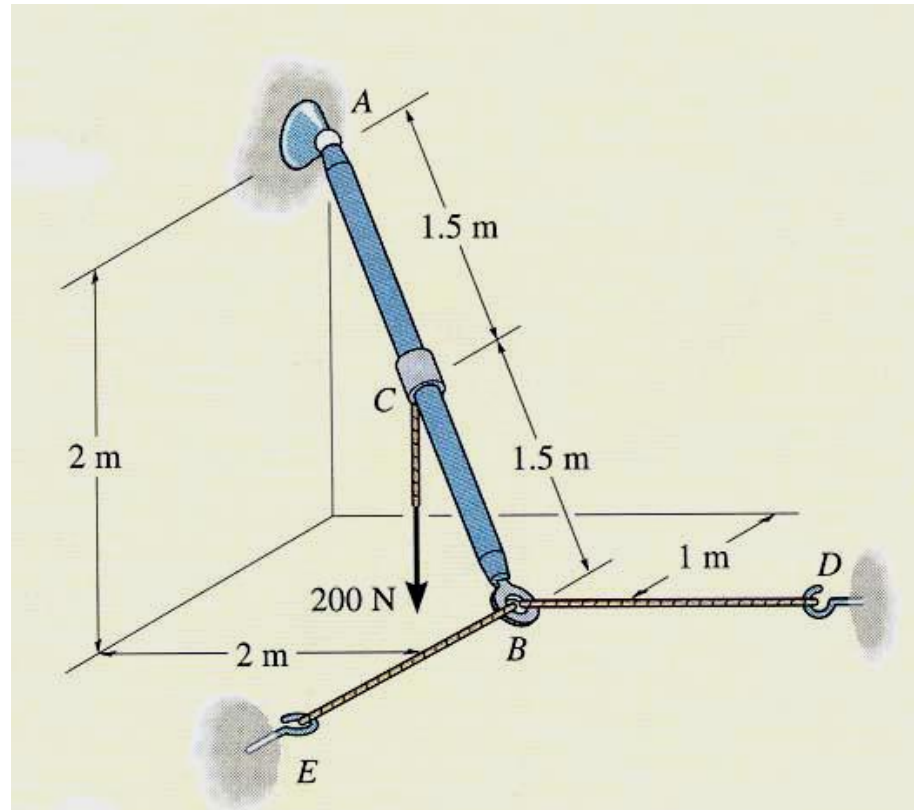
$$\underline{M_{AX} = 7200 \text{ N} \cdot \text{m}}, \quad \underline{M_{AY} = -10800 \text{ N} \cdot \text{m}}, \quad \text{and} \quad \underline{M_{AZ} = 0}$$

Note: For simpler problems, one can directly use three scalar moment equations, $\sum M_X = \sum M_Y = \sum M_Z = 0$



Question

1. The rod AB is supported using two cables at B and a ball-and-socket joint at A. How many unknown support reactions exist in this problem?



- 1) 5 force reactions
- 2) 5 force and 1 moment reaction
- 3) 3 force and 3 moment reactions
- 4) 4 force and 2 moment reactions

CONCEPT QUIZ (continued)

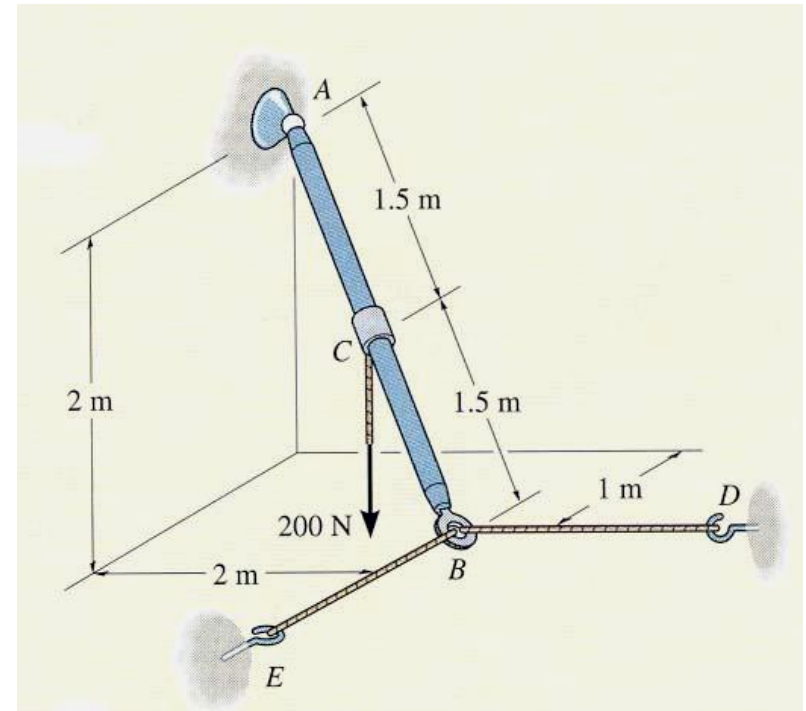
2. If an additional couple moment in the vertical direction is applied to rod AB at point C, then what will happen to the rod?

A) The rod remains in equilibrium as the cables provide the necessary support reactions.

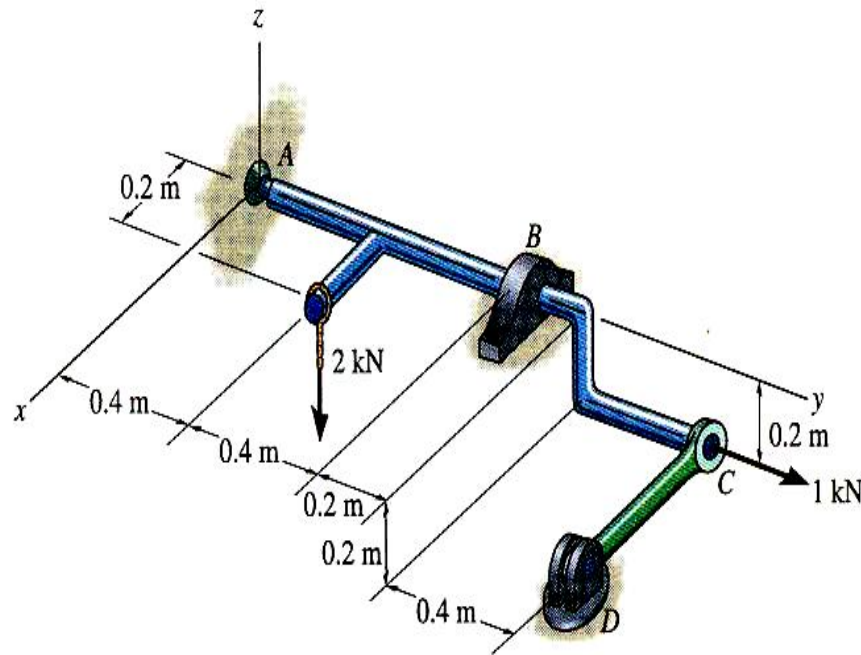
B) The rod remains in equilibrium as the ball-and-socket joint will provide the necessary resistive reactions.

C) The rod becomes unstable as the cables cannot support compressive forces.

D) The rod becomes unstable since a moment about AB cannot be restricted.



GROUP PROBLEM SOLVING



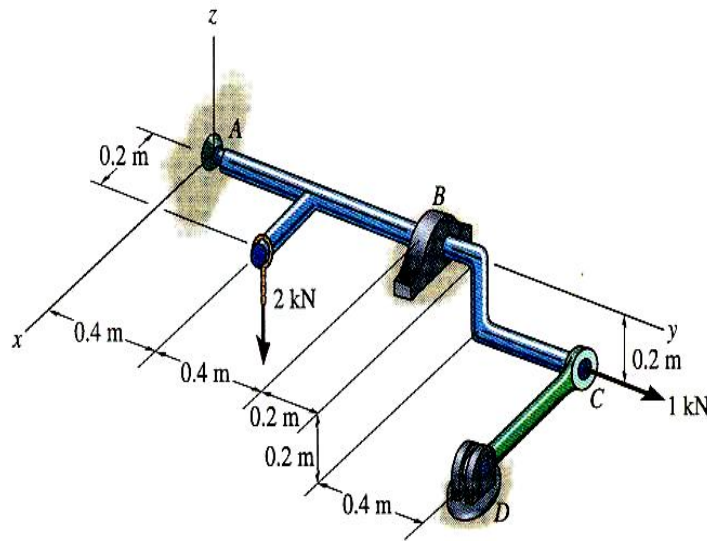
Given: A rod is supported by a ball-and-socket joint at A, a journal bearing at B and a short link at C. Assume the rod is properly aligned.

Find: The reactions at all the supports for the loading shown.

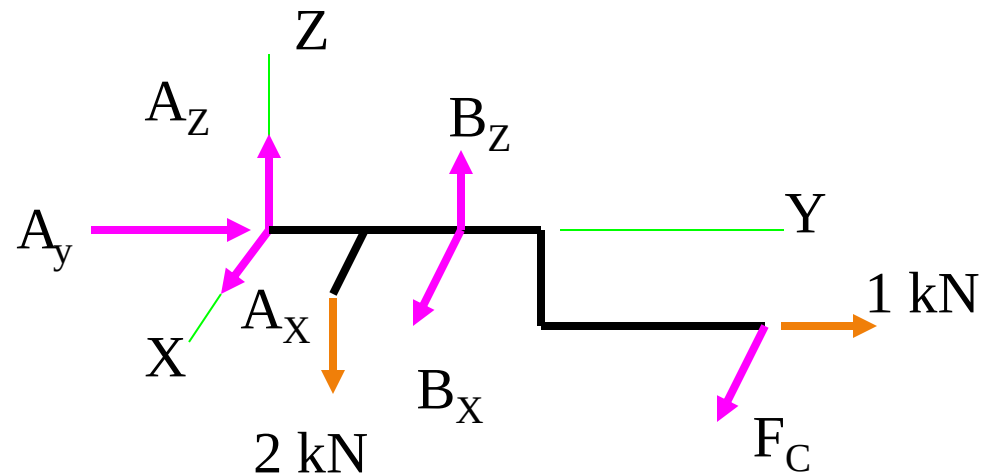
Plan:

- Draw a FBD of the rod.
- Apply scalar equations of equilibrium to solve for the unknowns.

GROUP PROBLEM SOLVING (continued)



A FBD of the rod:



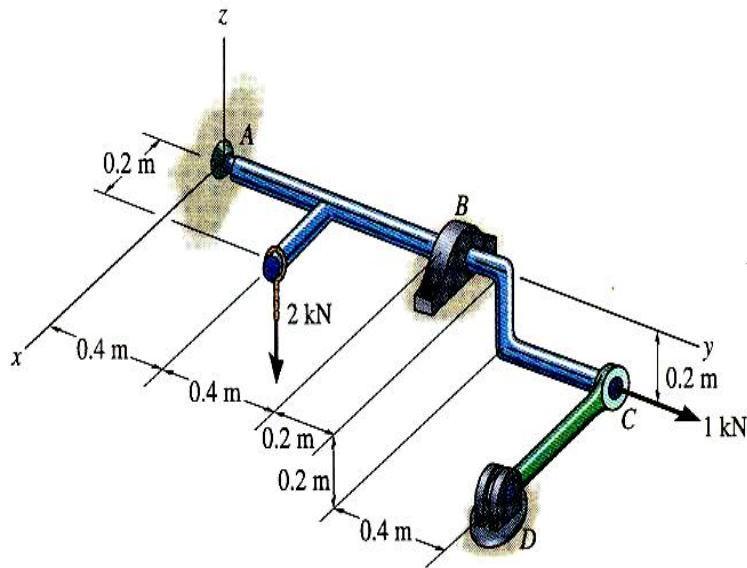
Applying scalar equations of equilibrium in appropriate order, we get

$$\sum M_Y = 2(0.2) - F_C(0.2) = 0 ; \quad F_C = 2 \text{ kN}$$

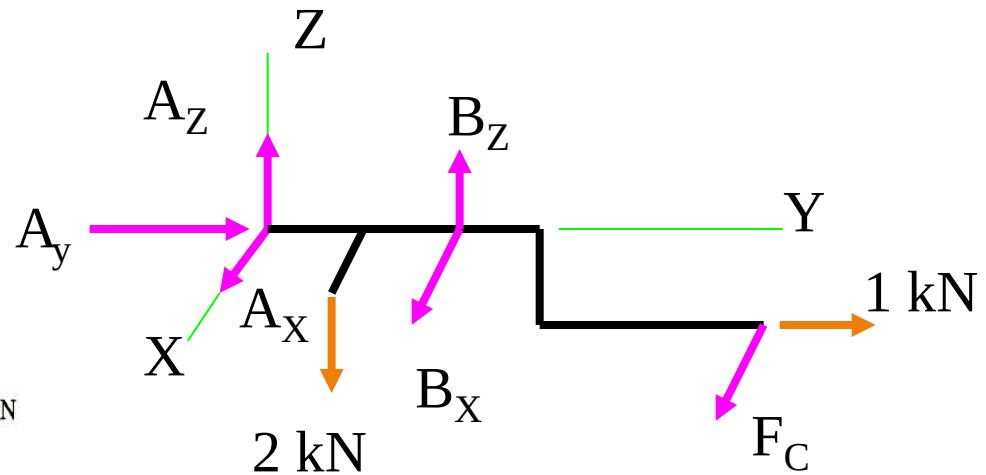
$$\sum F_Y = A_Y + 1 = 0 ; \quad A_Y = -1 \text{ kN}$$

$$\sum M_Z = -2(1.4) - B_X(0.8) = 0 ; \quad B_X = -3.5 \text{ kN}$$

GROUP PROBLEM SOLVING (continued)



A FBD of the rod:



$$\sum F_x = A_x - 3.5 + 2 = 0 ;$$

$$A_x = 1.5 \text{ kN}$$

$$\sum M_x = -2(0.4) + B_z(0.8) + 1(0.2) = 0 ;$$

$$B_z = 0.75 \text{ kN}$$

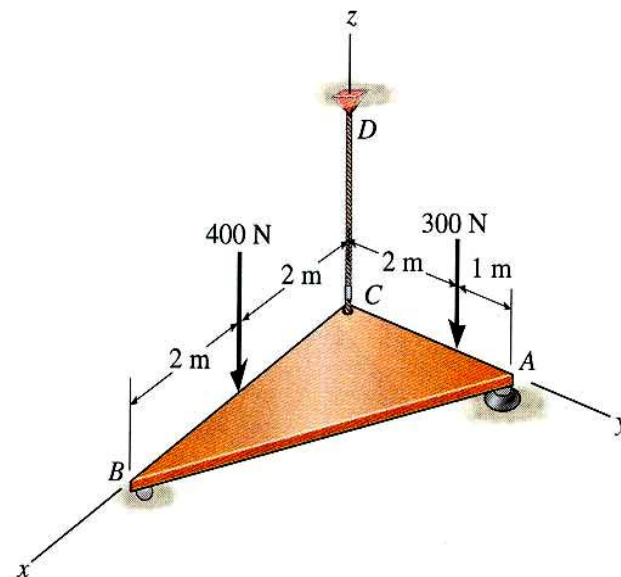
$$\sum F_z = A_z + 0.75 - 2 = 0 ;$$

$$A_z = 1.25 \text{ kN}$$

ATTENTION QUIZ

1. A plate is supported by a ball-and-socket joint at A, a roller joint at B, and a cable at C. How many unknown support reactions are there in this problem?

- A) 4 forces and 2 moments
- B) 6 forces
- C) 5 forces
- D) 4 forces and 1 moment



ATTENTION QUIZ

2. What will be the easiest way to determine the force reaction B_z ?

A) Scalar equation $\sum F_z = 0$

B) Vector equation $\sum \mathbf{M}_A = 0$

C) Scalar equation $\sum M_z = 0$

D) Scalar equation $\sum M_y = 0$

